2/4 B.Tech - THIRD SEMESTER

Basic Simulation Lab

Credits: 2

| Lecture: | | Internal assessment: 25 marks |
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| Lab | : 3 periods/week | Semester end examination: 50 marks |

Course Objectives:

EC3L1

The objective of this laboratory is

- To introduce MATLAB and use it as a computation and visualization tool in the study of Signals & Systems and Probability theory & Stochastic process.
- An introduction to MATLAB is first given to provide the students with the foundation they need in this lab.
- Students will then be exposed to the applications of MATLAB to signal analysis and system design.

Learning Outcomes:

Student will be able to

- Analyze various types of signals and sequences.
- Apply convolution and correlation operations on different signals.
- Determine the response of an LTI system to given signals.
- Plot the spectrum of a given signal using MATLAB.
- Verify the Sampling theorem.
- Synthesize Laplace transform and able to locate poles and zeros of a system.
- Compute various statistical properties of a random noise and verify whether it is stationary.

NOTE: Minimum of 10 experiments has to be performed and recorded by the candidate to attain eligibility for External Practical Examination.

List of Experiments:

- 1. Basic Operations on Matrices.
- 2. Generation of Various Signals and Sequences such as Unit impulse, Unit step, Square, Triangular, Sinusoidal, Ramp and Sinc functions.
- 3. Operations on Signals and Sequences such as Addition, Multiplication, Scaling, Shifting and Folding.
- 4. Finding Even and Odd Parts of a Signal or Sequence.
- 5. Verification of Linearity and Time Invariance properties of a given Continuous / Discrete-time system.
- 6. Convolution of Signals and Sequences.
- 7. Auto Correlation and Cross Correlation of Signals and Sequences.
- 8. Computation of Unit Sample and Unit Step Response of given LTI System.
- 9. Find the Fourier Transform of a given signal and plot its magnitude and phase spectrum.
- 10. Wave form synthesis using Laplace Transform.

- 11. Locating Poles and Zeros and obtain the pole-zero plot in S-plane for a given transfer function.
- 12. Generation of Gaussian Noise, Computation of its Mean, Mean Square values and its Skew, Kurtosis and PSD.
- 13. Verification of Sampling Theorem.
- 14. Removal of noise by autocorrelation/ cross correlation in a given signal corrupted by noise.
- 15. Checking a Random Process for Wide Sense Stationarity.